

Efficiency, intelligence and autonomy:

Maximising the carbon benefit from transport innovations

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#LowCVP16



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Automated Vehicles: Automatically Low Carbon?

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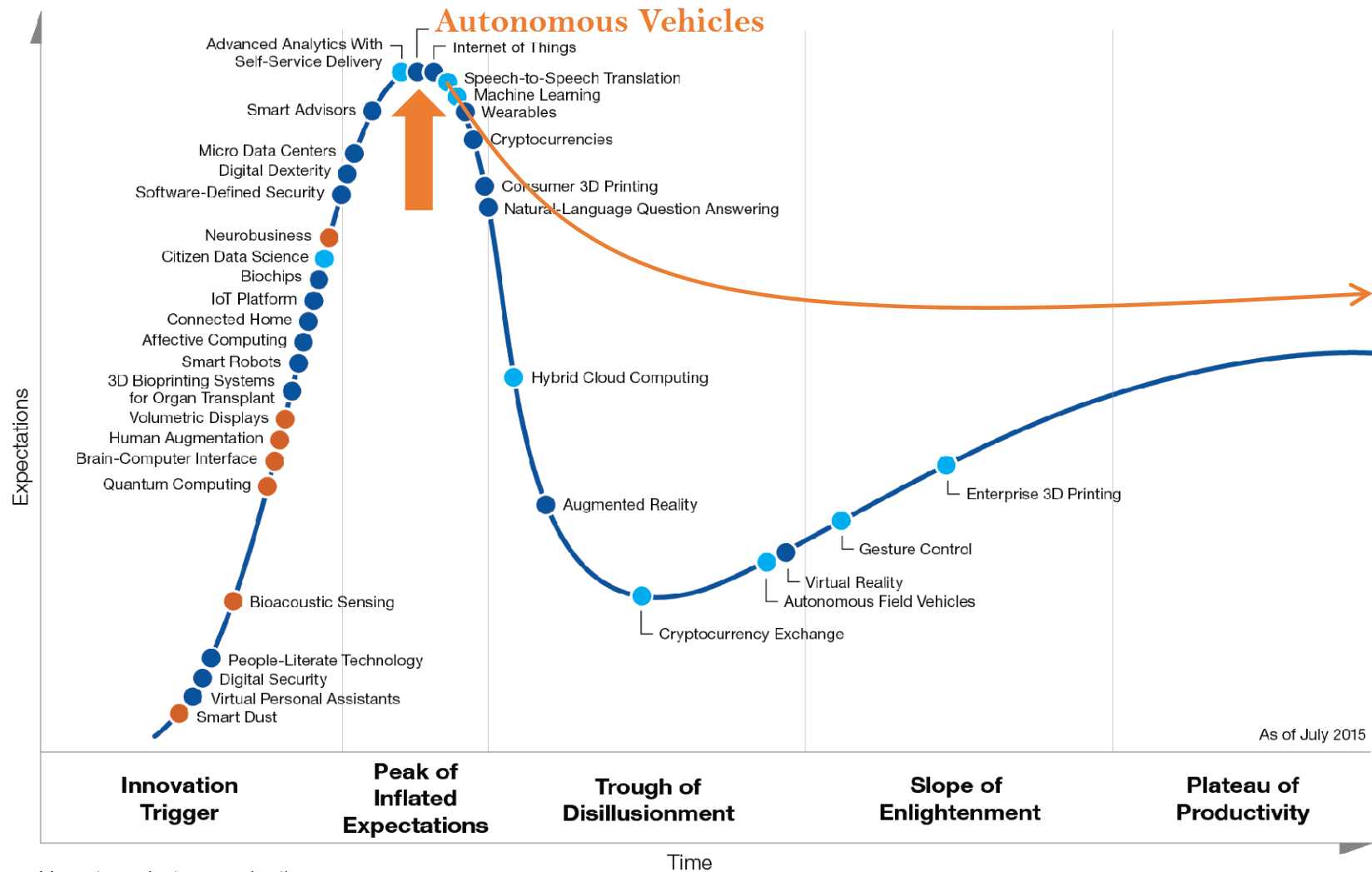
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LowCVP Conference, June 2016

Technology Hype Cycle!



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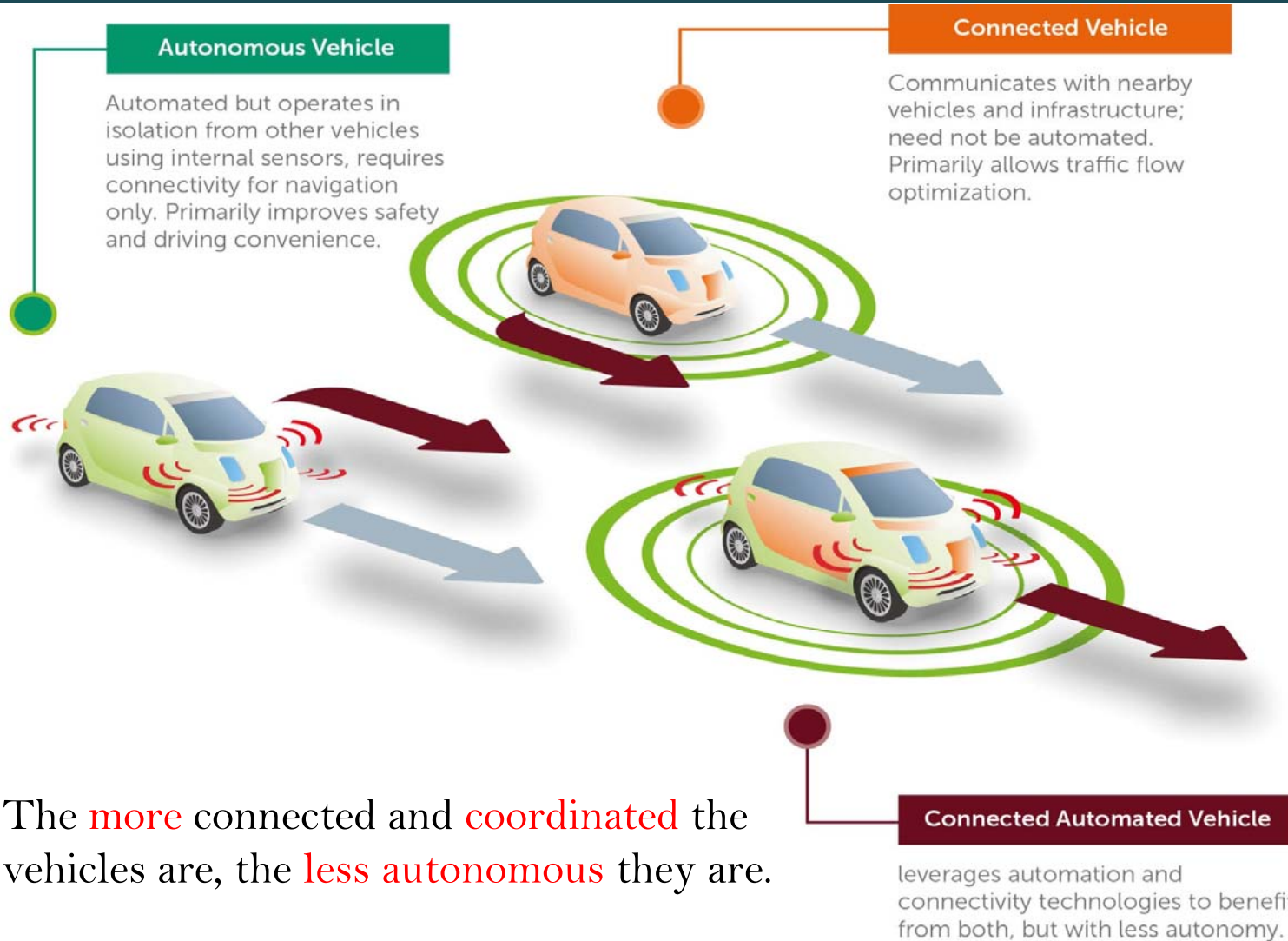
- What are the potential **travel**, **energy** and **carbon** impacts?
- Do we let **market** decide the development? Or, do we need to **plan** ahead to reap the **carbon benefits**?
- What are the **key areas** that require **attention** from policymakers?



Autonomous, automated, connected?



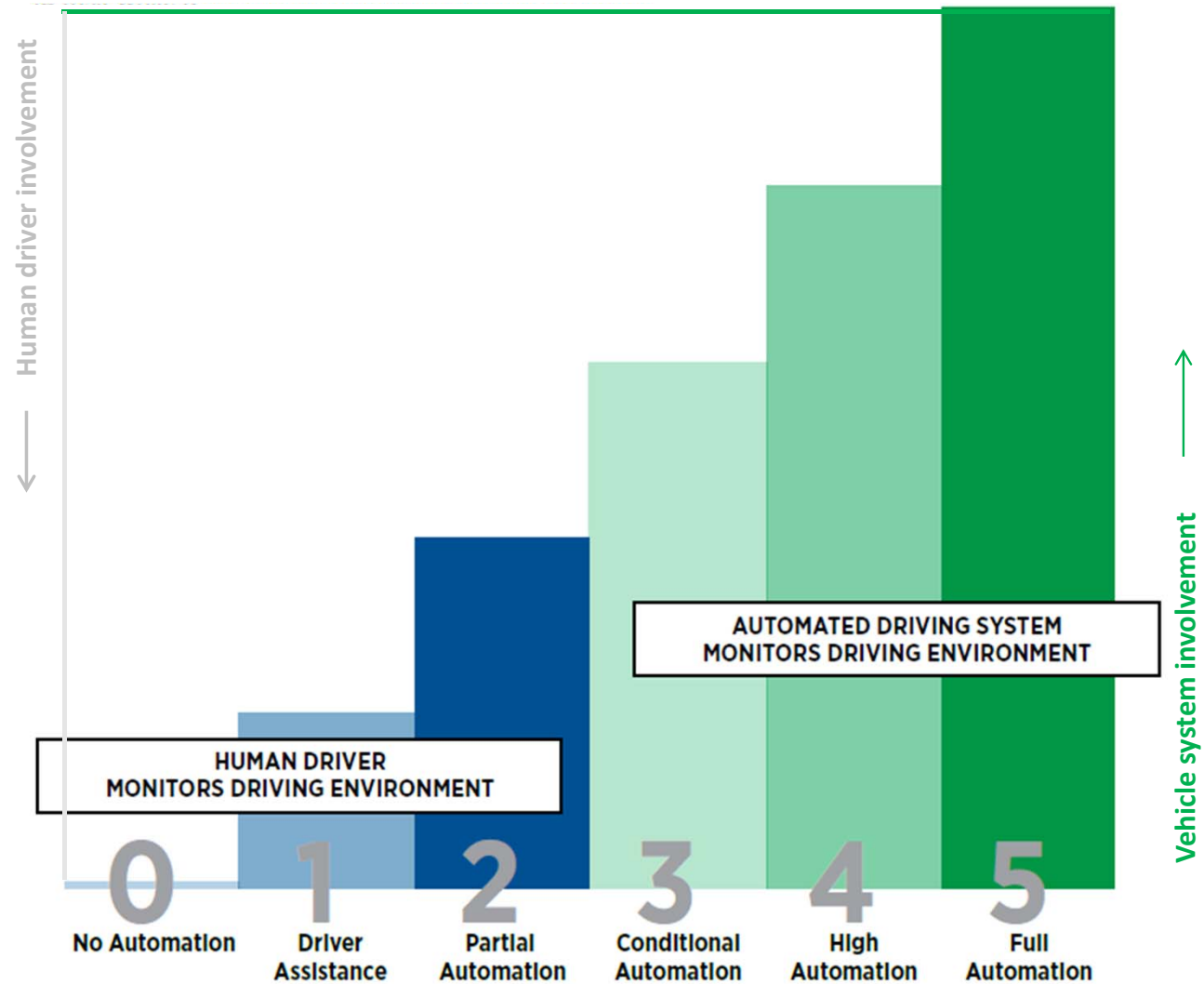
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Levels of automation



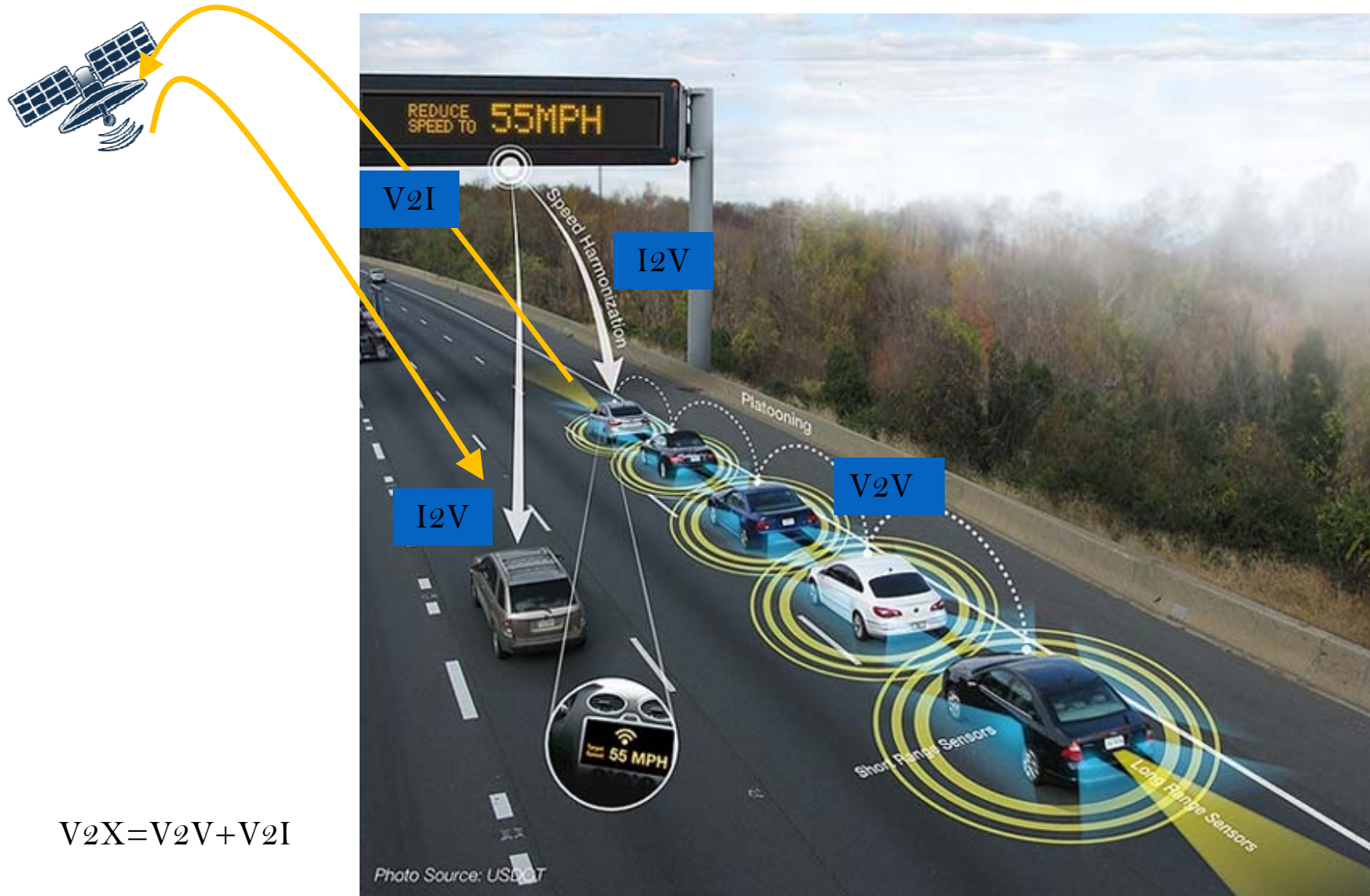
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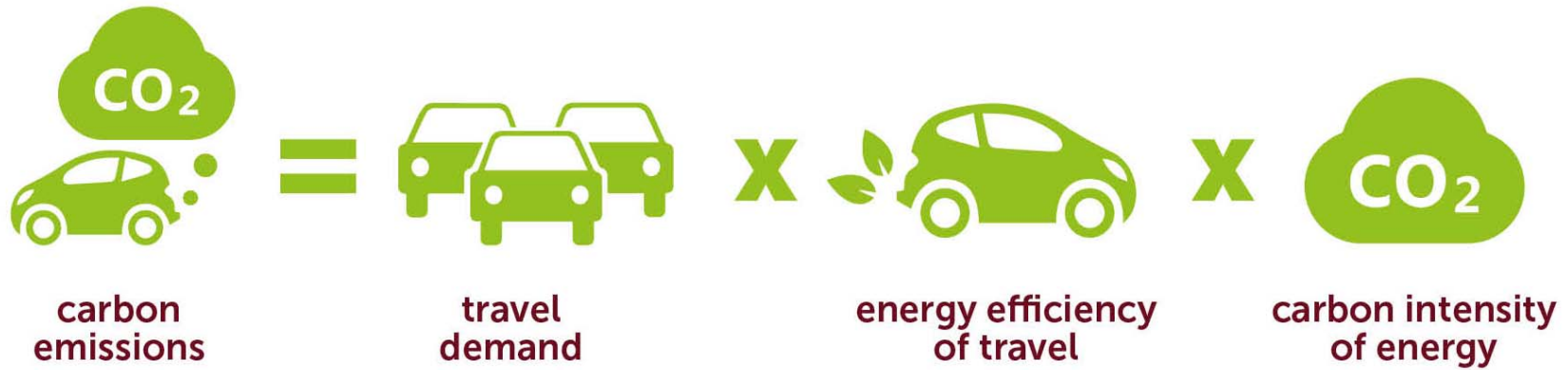
Connectivity & coordination

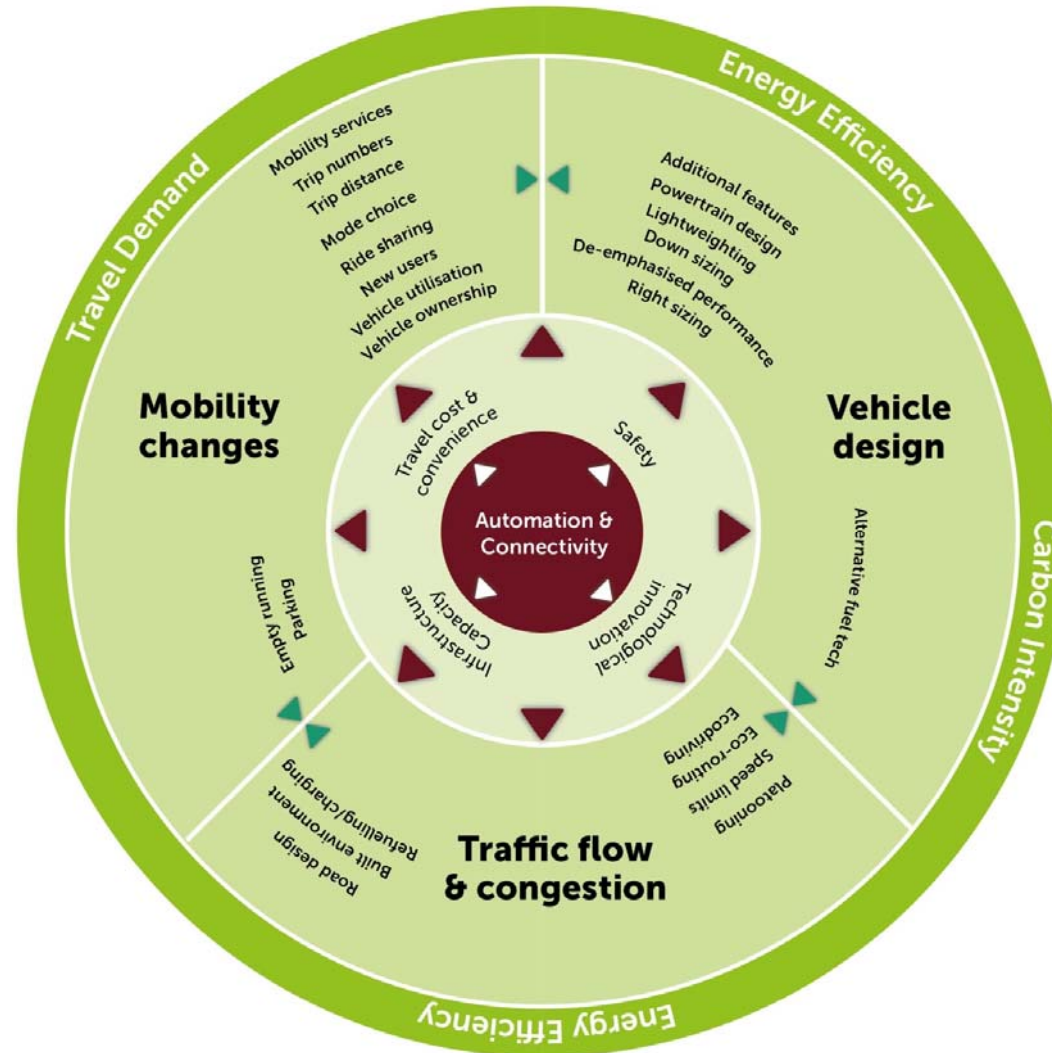


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Carbon equation





Energy efficiency



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Mechanisms	Energy effects	Automation level	Connectivity level
Traffic flow improvement	✓		V2X
Eco-routing	✓ ✓		V2X
Eco-driving	✓		V2X
<p>SE Early benefits from connectivity and connectedness</p> <p>P Potentially large benefits at high levels of automation and connectivity, but these benefits are highly uncertain, too</p> <p>A and depends on innovations in other areas</p>			
De-emphasized performance	✓ ✓		I2V
Lightweighting	✓ ✓		V2X
Rightsizing	✓ ✓ ✓		V2I, I2V

Travel demand



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Mechanisms	Energy effects	Automation level	Connectivity level
Distances (location choice)	XX		I2V
Modal shift	XXX		I2V
Trip number	X		I2V
New user groups	X		I2V, V2I
Mobility on demand, MaaS	✓✓✓ / X		I2V, V2I
Empty running	X		I2V, V2I

- Small impact at low levels of automation
- Step changes at high levels of automation
- Large uncertainty at high levels of automation
- Car ownership vs. car-share/mobility services major uncertainty



- Automation does not automatically mean EVs or FCVs, but several synergies between automation and low carbon fuel
- Unattended refuelling/recharging : annoyance reduced
- High utilisation in a mobility services future: cost efficiency
- Lightweighting allows more batteries: range anxiety reduced
- all related to full (driverless) automation
- Automatic electric driving for HEVs/PHEVs using Geofencing



Planning & coordination of stakeholders needed **to align** individual mechanisms toward the desired outcome

Net impact depends on **further innovations** in vehicle design

Incentivize manufacturers to provide **efficiency** optimizing features

Establishing **data** safeguarding & sharing **protocols**, and provisions for **smart connectivity** vital at **early stages** of development

Demand management key to mitigate any increases in car use

-Road user charge, LEZs, regulation of empty running

Support for new mobility services

Incentivize/limit sales and **use** of highly or **fully automated** cars to vulnerable users, mobility & transport service providers, or, only for **low carbon** propulsion

Public engagement necessary for acceptance & positive use behaviours



Automated Vehicles: Automatically Low Carbon?

..... Not yet, but holds promise!!

Thank you



- Planning & coordination of stakeholders needed to align individual mechanisms toward the desired outcome
- Establish data safety & sharing protocol to ensure smart connectivity at early stages
- Demand management will be required to mitigate against potential net increase in travel demand
- Policies to provide direction toward shared mobility services
- Beware of unintended travel & energy effects!!

Carbon emissions



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Mechanisms	Energy effect direction & size	Automation level required	Connectivity level required	Remarks
Traffic flow improvement & congestion mitigation	😊	1-5	V2X-2way	Step change at higher levels of automation & connectivity
Dynamic eco-routing	😊😊	1-5	V2X-2 way	
Automated eco-driving	😊	2-5	V2X, 2way	
Higher motorway speed limits	😞	2-5	V2X-2way	Only with regulatory changes
Vehicle platooning in motorways	😊	3-5	V2V	
Additional comfort & convenience features	😞	3-5	I2V	
De-emphasized performance	😊😊	4-5	I2V	
Light-weighting in city cars	😊😊	4-5	V2X-2way	Only with very high uptake & regulatory changes
Right-sizing	😊😊😊	5	V2I-2way	Only for MOD services



Table 2: Potential mechanisms for changes in **travel demand** due to automation and connectivity and their **energy effects** (adapted from Wadud et al.)¹⁹

Mechanisms	Energy effect direction & size	Automation level required	Connectivity level required	Remarks
Distances travelled (location choice)	☹️☹️	2-5	I2V	Step changes at levels 4-5
Modal shift	☹️☹️☹️	3-5	I2V	Step changes at levels 4-5
Trip Numbers	☹️	3-5	I2V	Step changes at levels 4-5
New user groups	☹️	4-5	I2V, V2I	Primarily at Level 5
Mobility on Demand	😊😊😊/☹️	5	I2V, V2I	Right-sizing needed for large reduction
Empty running of vehicles	☹️	5	I2V, V2I	Only at Level 5

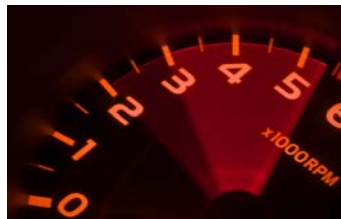
😊 Reduction in energy use.
 ☹️ Increase in energy use.

Mechanisms for energy effects



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Energy Efficiency



Travel Demand

Carbon emissions



	SAE level	Name	Steering, acceleration, deceleration	Monitoring Driving Environment	Fallback Performance of Dynamic Driving Task	System Capability (Driving Modes)	Timeline
Human monitors environment	0	No automation The full-time performance by the <i>human driver</i> of all aspects of the <i>dynamic driving task</i> , even when enhanced by warning or intervention systems				n/a	Now
	1	Driver assistance The <i>driving mode</i> -specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the <i>human driver</i> perform all remaining aspects of the <i>dynamic driving task</i>				Some driving modes	Now
	2	Partial automation The <i>driving mode</i> -specific execution by one or more driver assistance systems of both steering and acceleration/deceleration using information about the driving environment and with the expectation that the <i>human driver</i> perform all remaining aspects of the <i>dynamic driving task</i>				Some driving modes	Now
Car monitors environment	3	Conditional automation The <i>driving mode</i> -specific performance by an <i>automated driving system</i> of all aspects of the dynamic driving task with the expectation that the <i>human driver</i> will respond appropriately to a <i>request to intervene</i>				Some driving modes	2017
	4	High automation The <i>driving mode</i> -specific performance by an <i>automated driving system</i> of all aspects of the <i>dynamic driving task</i> , even if a <i>human driver</i> does not respond appropriately to a <i>request to intervene</i>				Some driving modes	2025
	5	Full automation The full-time performance by an <i>automated driving system</i> of all aspects of the <i>dynamic driving task</i> under all roadway and environmental conditions that can be managed by a <i>human driver</i>				All driving modes	2025

Results (USA)



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